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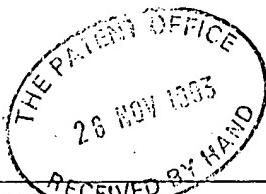
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Jg-1807

26 NOV 1993

30NOV1993#003C7537 PAT 1 77 UC 25.00

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- 1 Please give the title APPARATUS FOR THE REMOTE
of the invention MEASUREMENT OF PHYSICAL PARAMETERS

② Applicant's details

First or only applicant

- 2a If you are applying as a corporate body please give:

Corporate name
SENSOR DYNAMICS LIMITED

Country (and State
of incorporation, if
appropriate)

- 2b If you are applying as an individual or one of a partnership please give in full:

Surname

Forenames

2c In all cases, please give the following details:

Address 3 Abbas Business Centre,
Itchen Abbas,
Winchester,
Hampshire,

UK postcode SO21 1BQ
(if applicable)

Country UK

ADP number
(if known)

6026736001

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2d, 2e and 2f: If there are further applicants please provide details on a separate sheet of paper.

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<p>① Address for service details</p> <p>3a Have you appointed an agent to deal with your application?</p> <p>Yes <input checked="" type="checkbox"/> No <input type="checkbox"/> go to 3b</p> <p style="text-align: center;">↓ <i>please give details below</i></p> <p>Agent's name GRAHAM JONES & COMPANY</p> <p>Agent's address 77 Beaconsfield Road, Blackheath, London,</p> <p>Postcode SE3 7LG</p> <p>Agent's ADP number 2097001</p>	
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- 4 Agent's or applicant's reference number (if applicable)

Jg-1807

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- 8 Please supply duplicates of
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8a Please fill in the number of sheets for each of the following of
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Continuation sheets for this Patents Form

Claim(s)	11
Abstract	10

8b Which of the following documents also accompanies the application?

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Form 7/77

Patents Act 1977

① Application details

1a Please give the patent application number (if known):

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SENSOR DYNAMICS LIMITED

**② Title of invention APPARATUS FOR THE REMOTE
MEASUREMENT OF PHYSICAL PARAMETERS**

2 Please give the title of the invention:

③ Derivation of right

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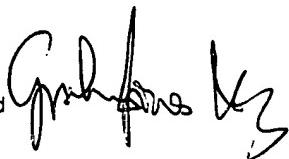
by virtue of agreement between the applicant
of the one part and the inventors of the
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4 I believe the person(s) named overleaf (and on any supplementary copies of this form) to be the inventor(s) of the invention for which the patent application has been made. I consent to the disclosure of the details contained in this form to each inventor named.

Please sign here ➔

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Please turn over ➔

Please put the full name(s) and address(es) of the inventors in the boxes below:

Please underline the surnames or family names.

Erhard Lothar Edgar Kluth,
The Town Mill,
Mill Hill,
Alresford,
Hampshire,
SO24 2DD

ADP number (if known):

612668001

OR

Malcolm Paul Varnham,
18 De Lucy Avenue,
Alresford,
Hampshire,
SO24 9EU

ADP number (if known):

6457147001

OR

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Have you signed the declaration overleaf?

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APPARATUS FOR THE REMOTE MEASUREMENT OF PHYSICAL PARAMETERS

The invention relates to apparatus for the remote measurement of physical parameters in which the advantages of optical fibre cables and optical fibre sensors are exploited for use within the oil industry, particularly for use with remote subsea satellite wells and oil refinery stacks, and such that the sensors may be recovered and or replaced.

As oil and gas reserves have been consumed over the years, the extraction of the oil and gas has become increasingly more difficult under more demanding conditions. Accordingly, there is a need for the reserves to be more widely monitored to a higher quality than hitherto, and this is particularly so for oil and gas reserves which lie beneath the sea bed. Optical fibre sensors, together with optical fibre cables to link the sensor to the measurement instrumentation, are being developed for this purpose since they offer specific advantages, particularly in the ability to withstand extremes of high pressure and temperature. Furthermore, such optical fibre sensors may be of a structure and diameter similar to those of the optical fibre cable itself. There are specific advantages in being able to remove and replace a sensor for the purposes of calibration, repair, and enhancement, but this is notoriously difficult to do within the oil industry, particularly with subsea wells because of the harsh environmental conditions and the sometimes considerable distances of tens kilometres between the desired point of measurement at the bottom of a well and the point of use of the information at the production platform. In addition, the substantial demands made on the equipment involved in extracting oil and gas make it very difficult and expensive to solve measurement problems. Hence, it is very desirable for there to be apparatus which is capable of isolating the problems of measurement from all the other challenges of exploiting the oil or gas reserves, particularly if it is not necessary to install the measurement system at the same time as the other equipment.

The chemical industry has a requirement to monitor discharges from stacks such as chimneys and pipes. In a typical processing site, many stacks will exist over many acres of ground. Currently, this monitoring is achieved by installing ladders and platforms on the outside of stacks, installing expensive equipment on the platforms, and sending trained personnel up the ladders to the platforms to perform measurements on a regular basis. An altogether better approach would be to have an apparatus which is capable of isolating

the problems of measurement from the challenge of getting people and equipment into the remote measurement location, particularly if it is not necessary to install the measurement system at the same time as the other equipment.

5 An aim of the present invention is to improve on known apparatus by simplifying the apparatus needed to install and retrieve an optical fibre sensor for the measurement of physical parameters, and a further aim is to do so with minimum disturbance to the other operations taking place during oil and gas production.

10 According to a non-limiting embodiment of the present invention, there is provided apparatus for the remote measurement of physical parameters, comprising sensing means for sensing one or more physical parameters, instrumentation means for interrogating the sensing means and making a measurement, cable means for communicating between the sensing means and the instrumentation means, container means for containing the sensing means and the cable means prior to installation of the sensing means, container holder means for providing a support for the container means at a convenient location, channel means for providing a channel between the container holder means and a measurement location where the channel is suitable for accepting the cable means and the sensing means, channel connector means for making a channel connection between the container means and the channel means, and cable installation means for installing the sensing means and cable means from inside the container means into the channel means and placing the sensing means at the measurement location.

15 20 25 30 The apparatus may include power supply means for supplying power to the apparatus.

35 The apparatus may include container insertion means for inserting the container means into the container holder means so that the channel connection is made.

40 The sensing means may be one or more optical fibre sensors. Preferably the sensing means may be of dimensions permitting the channel means to be a commonly available component. Also preferably, the optical fibre sensor may be of a structure and diameter comparable with those of the cable means.

The instrumentation means may be such that a measurement may be recorded at the time of occurrence for use at a later time. The

Instrumentation means also may be such that the measurement is transmitted to a receiver situated elsewhere using a non-contact method such as radio wave communication.

5 The cable means may be one or more optical fibre cables containing one or more optical fibre waveguides. Preferably, the optical fibre cable may be one commonly used within the telecommunications industry.

10 The container means may be a single unit or may be a plurality of units, each for the purpose of deploying embodiments of the sensing means.

15 The container holder means may be such as to accommodate the container means as a single unit, or may be such as to accommodate a plurality of units for the purpose of deploying embodiments of the sensing means.

20 The channel means may be one or more tubes with one or more cavities. Preferably, the channel means may be chemical injection or hydraulic tubing and, more preferably, the channel means may be commonly available quarter inch bore high pressure hydraulic tubing. The channel means may also be a natural cavity in the environment containing a guide such as a cable or a monorail or slotted rod.

25 The cable installation means may use the force of gravity, or, preferably, may be power assisted using hydraulic pressure and/or hydraulic drag forces.

30 The power supply means may wholly reside within the container means. Alternatively, the power supply means may be located outside the container means, in which case there is further provided power connector means for making a power connection between the power supply means and the components of the apparatus inside the container means, where the power connection is made when the container means is located in the container holder means and the power connection is broken when the container means is removed from the container holder means. The power supply means may supply power in a combination of a variety of forms, such as electrical, magnetic, hydraulic, pneumatic
35 and optical power.

40 The container insertion means may be manual for applications where the container holder means is situated at a benign location. For other and more extreme environments, the container insertion means

may involve the use of automatic apparatus, such as subsea remote operated vehicles, for example when the container holder is situated on a sea bed.

5 In an embodiment of the present invention, the apparatus is one in which the cable installation means includes cable removal means for removing the sensing means and cable means from inside the channel means back into the container means, the channel connector means includes channel break means for breaking the connection
10 between the container means and the channel means, and the container insertion means includes container removal means for removing the container means from the container holder so that the channel connection is broken.

15 In an embodiment of the present invention, the apparatus is one in which the instrumentation means is contained within the container means.

20 In another embodiment of the present invention, the apparatus is one in which the instrumentation means is situated outside the container means, and there is further provided communication means for connecting the cable means inside the container means to the instrumentation means. The communication means may include communication connector means for making a signal connection
25 between the inside and the outside of the container means, where the signal connection is made when the container means is located in the container holder means and the signal connection is broken when the container means is removed from the container holder.

30 In another embodiment of the present invention, the apparatus is one in which the instrumentation means comprises an inside instrumentation means situated inside the container means and an outside instrumentation means situated outside the container means, and there is further provided instrumentation communication means for communicating between the inside instrumentation means and the outside instrumentation means. The instrumentation communication means may include instrumentation communication connector means for making an instrumentation connection between the inside instrumentation means and the outside instrumentation means of the container means, where the instrumentation connection is made when the container means is located in the container holder means and the instrumentation connection is broken when the container means is removed from the container holder.

The apparatus may be such that the communication connector means may be combined with power supply connector means.

5 Figure 1 is a diagram of an embodiment the present invention in which the instrumentation means and power supply means are contained within the container means;

10 Figure 2 is a diagram of an embodiment of the present invention, in which the power supply means and instrumentation means are external to the container means;

15 Figure 3 is a diagram of an embodiment of the present invention in which details of the cable installation means are shown;

15 Figure 4 is a diagram of an embodiment of the present invention with details of the cable installation means;

20 Figure 5 is a diagram of an embodiment of the present invention with details of the cable installation means;

Figure 6 is a diagram of an embodiment of the present invention with details of the cable installation means;

25 Figure 7 is a diagram of an embodiment of the present invention where more than one container means are installed in a single container holder means;

30 Figure 8 is a diagram of an embodiment of the present invention where more than one container means are installed in a single container holder means;

35 Figure 9 is a diagram of an embodiment of the present invention where more than one container means are installed in a single container holder means; and

Figure 10 is a diagram of an embodiment of the present invention detailing an aspect of the communication means.

40 With reference to Figure 1, a container means 4 contains sensing means 1, instrumentation means 2, cable means 3, cable installation means 9, and power supply means 10. The container means 4 is inserted with container insertion means 11 into container holder

means 5 which is situated at some convenient location in relation to a measurement location 7 where a measurement is to be made. As the container means 4 is inserted into container holder means 5, channel connector means 8 makes a channel connection between channel means 6 and the container means 4. The channel means 6 provides a channel between the container holder means 5 and the measurement location 7 suitable for accommodating sensing means 1 and cable means 3. With container means 4 located in container holder means 5 such that the channel connection is made, cable installation means 9 may be operated so that sensing means 1 and cable means 3 are passed into channel means 6 until sensing means 1 reaches the measurement location 7. The apparatus may then be used to measure the desired parameter and either store the result in instrumentation means 2 for later use, or transmit the result to an external receiver (where there may be additional processing) using a form of non-contact communication.

With reference to Figure 2, the container means 4 contains the sensing means 1, the cable means 3, and the cable installation means 9. The container means 4 is inserted using the container insertion means 11 into the container holder means 5 which is situated at some convenient location in relation to the measurement location 7. As the container means 4 is inserted into container holder means 5, the channel connector means 8 makes the channel connection between the channel means 6 and the container means 4. A communications connector means 22 makes a connection between communication means 21 and the container means 4 where the communication means 21 links the communications connector means 22 to the instrumentation means 2. The communication means 21 and communications connector means 22 also provide the power connection between the power supply means 10 and the container means 4. After the container means 4 has been inserted in the container holder 5 and the channel connection, and the communications connection, have been made, the sensing means 1 may be installed as described with reference to Figure 1, and the apparatus may then be used to measure the desired parameter.

Figure 3 shows an embodiment of the present invention which utilises hydraulic power which may be provided by the power supply means 10. The hydraulic power is communicated to the container means 4 via the communication cable means 21 and communications connector means 22. The hydraulic power is used for deploying and/or retrieving the sensor means 1 and cable means 3.

The container means 4 contains container hydraulic channel means 31, which preferably may be convenient size hydraulic tubing, which connect to the channel means 6 via the channel connector means 8. The channel means 6 is preferably convenient size hydraulic tubing with a forward and return path to and from the measurement location 7. The channel connector means 8 is preferably hydraulic "stab" connectors which seal the hydraulic path when the connection is broken.

Valve means 32 are provided in the container to control the hydraulic flow. These are preferably hydraulic valves which may be controlled from signals communicated via the communication cable means 21.

The cable installation means 9 includes a strength member means 33, strength member supply means 34, and a cable combination means 35 which combines the strength member means 33 and the cable means 3 to make a combined cable means 36.

The strength member supply means 34 may be a drum of strength member means 33 wound onto a spooler, which may be a motorised system such that the cable can be spooled out under a controlled low tension, and/or spooled back under a controlled tension.

The strength member means 33 may be a cable with an internal cavity and a slit which opens up as it passes over a wheel 37. The cable means 3 may be fed into the internal cavity on the wheel 37 to form the combined cable means 36.

The strength member means 34 enters the container hydraulic channel means 31 via a sealing means 38 which may be a "stuffing box" i.e. the seal design allows the cable to be pulled through with minimum leakage.

The cable means 3 is wound onto a cable spooler means 39. One end of the cable means 3 is passed through a sealing means 38 to the cable combination means 35.

The other end of the cable means 3 is connected to a rotary connector means 40 which connects to the connector means 22 via a connecting cable means 41. The rotary connector means 40 allows the cable spooler means 39 to rotate (thus spooling the cable means in or out) without twisting the cable means 3 between the cable spooler means 39 and the connector means 22.

The strength member means 33 has a surface which offers impedance to fluid flow in hydraulic channels. This may be achieved with surface roughness, beads attached to the surface, or by adding beads or O-rings at the cable combination means 35. When hydraulic flow is activated around the hydraulic pathway comprising the hydraulic lines in the communication cable means 21, the container hydraulic channel means 31 and the channel means 6, this induces a

force on the combined cable means 35 thus deploying the combined cable means 36 along the channel means 6.

Reversing the hydraulic flow either by suitable valves and hydraulic channels (not shown) in the container means 4 or by

5 reversing the flow at or near the power supply means 10 (which may be on an oil or gas production platform) allows the sensing means to be recovered from the measurement location 7 into the container means 4. This recovery can be assisted by increasing the tension on the strength member supply means 34 such as to keep the combined cable means 36 in tension.

10 Additional hydraulic forces can be generated by designing the sensor means 1 such that it is housed in a package (not shown) which offers hydraulic impedance. The package (not shown) would have to be suitably designed such that it did not cause hydraulic instabilities

15 during extraction.

Deployment can be similarly assisted by deploying the strength member means 33 around the channel means 6 and back to the container means 4 prior to combining the strength member means 33 and cable means 3. Mechanical apparatus(not shown) may then grip the

20 strength member means 33 and apply tension.

25 The ability to retrieve the sensing means 1 allows calibration and servicing. The container means 4 may have design features which facilitate servicing such as a lid (not shown) and a seal (not shown) as well as design features which facilitate calibration.

Figure 4 shows an embodiment of the present invention where the cable means 3 is preloaded into the container means 4 in a cable winding support 51 where the winding method allows the cable means 3 to be pulled from the cable winding support 51 without twisting the cable means 3. The cable means 3 can thus be joined to the connector means 22 without using a rotary connector means 40 (Figure 3).

The container hydraulic means 31 includes a deployment path 52 and an extraction path 53 together with controlling valves 54. Sensor deployment is achieved by passing fluid down the deployment path 52 and around the hydraulic circuit as before. Sensor extraction is achieved by reversing the hydraulic flow, closing the deployment path 52 and opening the extraction path 53. The extraction path includes a receptacle 55 into which the cable means 3 will be stored.

40 Alternatively, the sensing means 1 may actuate a mechanical switch (not shown) to release tension on the strength member spooler means and to close the controlling valve on the extraction path 53. The sensing means 1 may be calibrated using a reference sensor 56.

5 Figure 5 shows an alternative method for repackaging the cable means 3 during retrieval. In this instance a winding machine 61 is provided which rewinds the cable means 3 without twisting the cable means 3. Such winding methods are commonly used in winding balls of string or wool.

10 Figure 6 shows an alternative method for repackaging the cable means 3 during retrieval. A cable severing means 71 powered by a solenoid 72 or other convenient actuating means severs the cable means 3 allowing the cable means 3 to be spooled onto the strength member spooler means 34.

15 Figure 7 shows an embodiment of the present invention where the container holder means 83 is such that a plurality of separate independent container means 4 are loaded. These container means 4 may each be interconnected to the instrumentation means 2 via local communication cable means 81, a master connector means 82, and a single communication cable means 9. These cables and connectors providing the pathways for hydraulic power, electrical power, 20 electrical signals, and optical signals. Each container means 4 may be individually connected to separate independent measurement locations 7 by separate independent channel means 6.

25 Alternatively, the separate independent container means 4 may be addressably connected to more than one measurement location 7 using an addressable distribution means 91 as shown in Figure 8. By way of example, one of the measurement locations 7 is connected to two container means 4 by channel means 6 which may comprise hydraulic lines. The hydraulic lines are connected with Y-junctions 30 92. Valves 93 are opened or closed in order to connect a closed-loop hydraulic path between the chosen container means 4 and the measurement locations 7 and back to the same container means 4 again.

35 Figure 9 shows an embodiment of the present invention in which container holder means 84 holds a carrier 101 which can be bring selected containers 112 to the surface of the sea by means of selection mechanism 102 for sensor means 1 replacement, servicing, and calibration.

40 A marker buoy 103 may be released (on command from signals supplied along the communication means 21) to the surface of the sea carrying marker buoy cables 104 with it which are attached to the carrier 101.

A support vessel (not shown) may retrieve the marker buoy 103 and send down a video pod (not shown) to the carrier 101 on one or more of the marker buoy cables 104 which may locate itself onto a marker buoy platform 105. The video pod (not shown) would inspect the installation and ensure that no cables were tangled and the installation is otherwise in order.

The sensing means 1 from selected measurement locations 7 is retrieved into the appropriate container means 112. The chosen container means 112 are engaged onto the carrier 101 by the selection mechanism 102 and the carrier 101 winched to the surface and hauled onto the ship using the marker buoy cables 104. The lifting of the carrier 101 may be assisted by floatation means 106 which may be floatation bags or the carrier 101 may be deliberately buoyant.

As the carrier 101 is winched to the surface, container holder cables 107 are paid out from container holder cable spoolers 108 on the container holder means 5. The container holder cable spoolers 108 may share a common drive.

A cable 109, containing optical fibre and power, may be connected between the cable means 3 to the master connector means 82 via a container spooler 110 attached to the outside of the container means 112.

With reference Figure 10, both ends of the cable 109 may be wound onto the container spooler 110 such that when the container spooler 110 pays cable 109 out, both ends are paid out simultaneously. Similarly, when the container spooler 110 spools in, both ends of the cable 109 are wound simultaneously via the spooler guiding mechanism 121. The purpose of the spooler is to ensure that as the carrier 101 is lifted, the cable entering into the container means 112 does not twist. The container means 112 may therefore seal the entry of the cable at the container seal 122 and the cable 109 may be connected to the cable means 3 via appropriate joining methods such as fusion splicing, this joining being preferably carried out in the ship when the carrier is on board. This advantageously helps improve reliability.

With reference to Figure 9, when servicing of the carrier 101 is finished, replacement of the sensing means 1 is finished, and calibration of the sensing means 1 is finished, the carrier 101 is lowered back to the container holder means 5. The motion of the carrier 101 is controlled by the container holder cable spoolers 108 and by control means (not shown) from the ship which may include ropes (not shown) connected between the ship and the carrier 101. Location of the carrier 101 may be achieved by carrier location means 111 which may include passing the container holder cables 107

through guides (not shown) for approximate location, and a mating conical connection (not shown) for fine location. Once the carrier 101 is located, channel connector means 8 and communication connect means 22 made, the sensing means 1 may be deployed.

5

It is to be appreciated that the embodiments of the invention described above with reference to the accompanying drawings have been given by way of example only and that modifications and additional components may be provided to enhance the performance of
10 the apparatus.

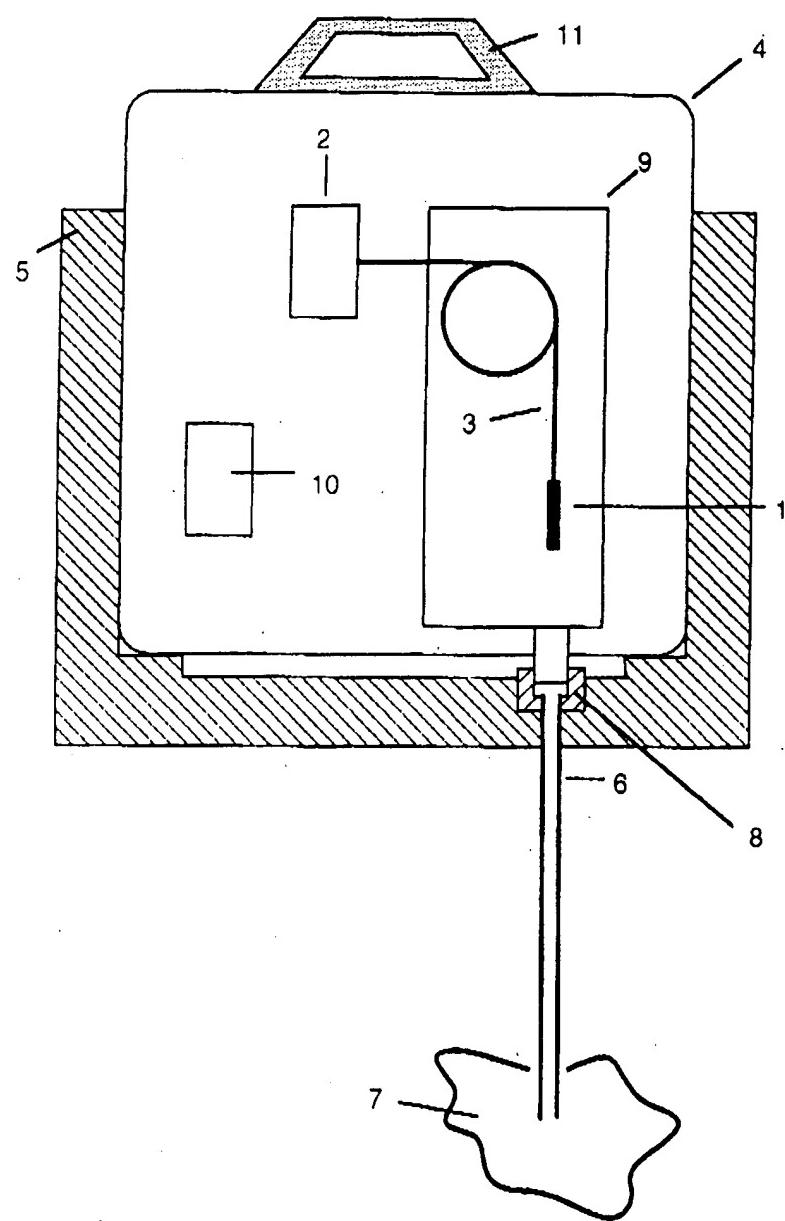


Figure 1

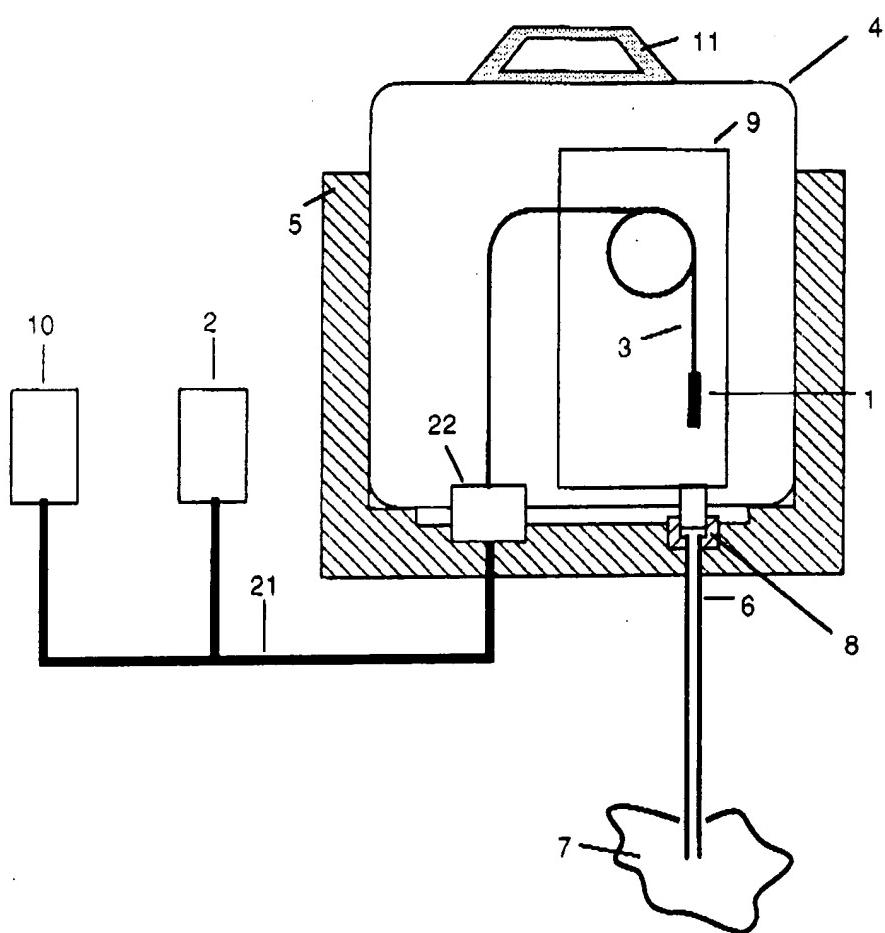


Figure 2

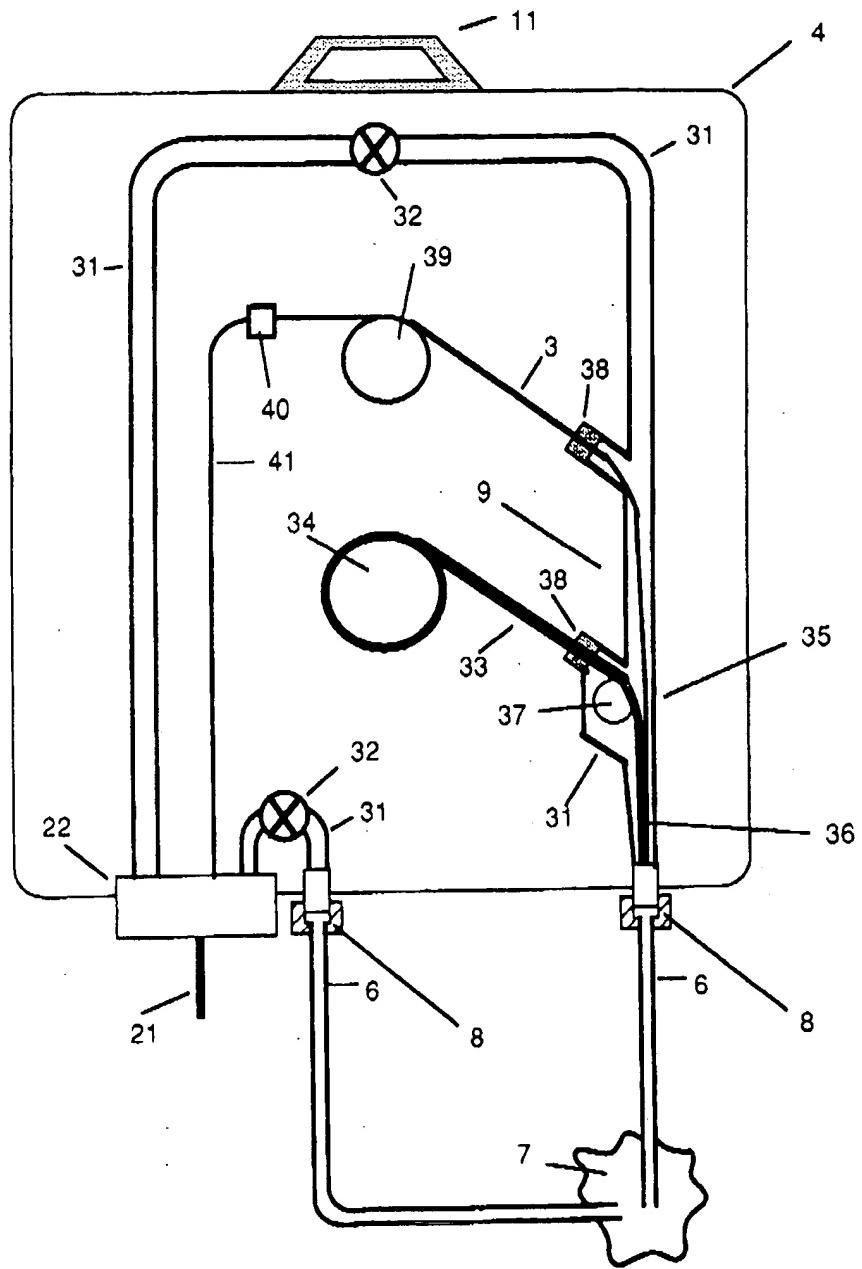


Figure 3

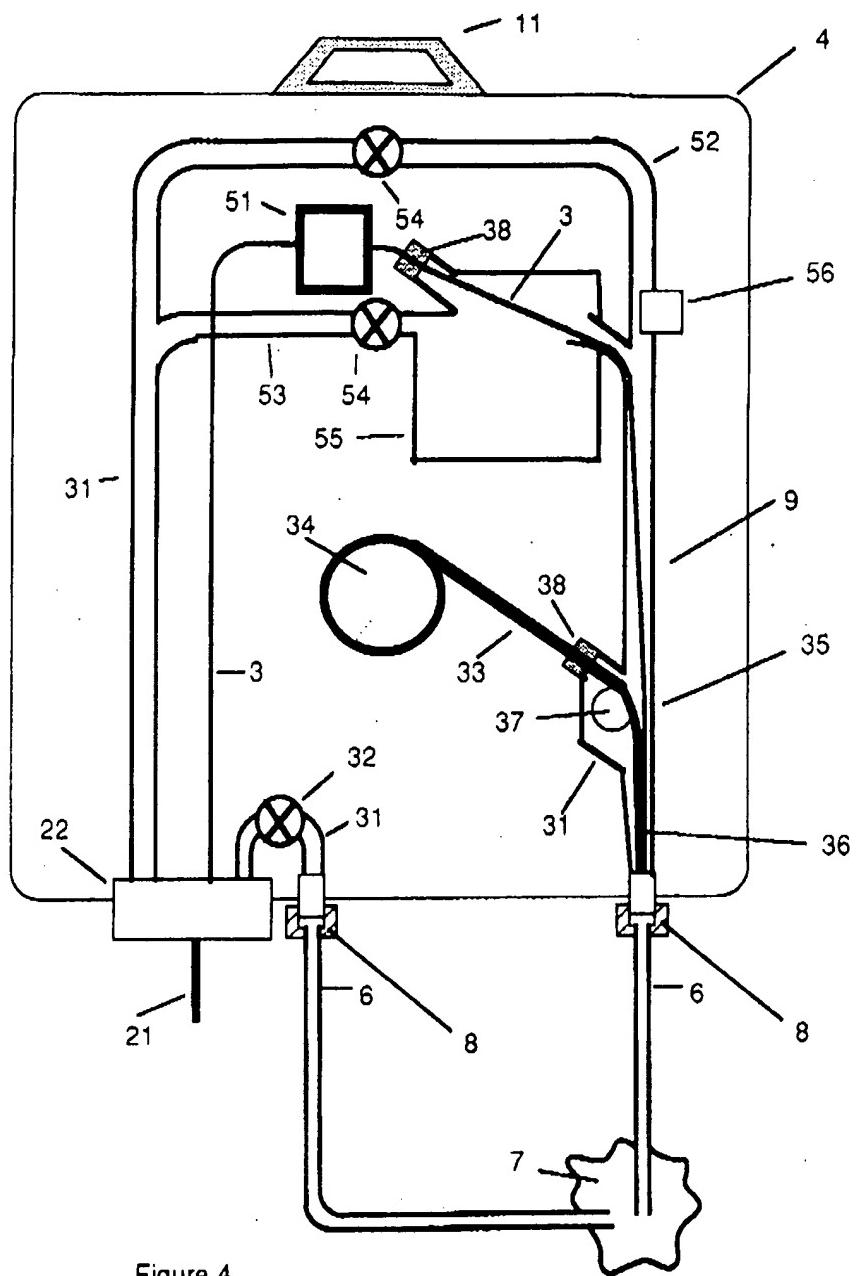


Figure 4

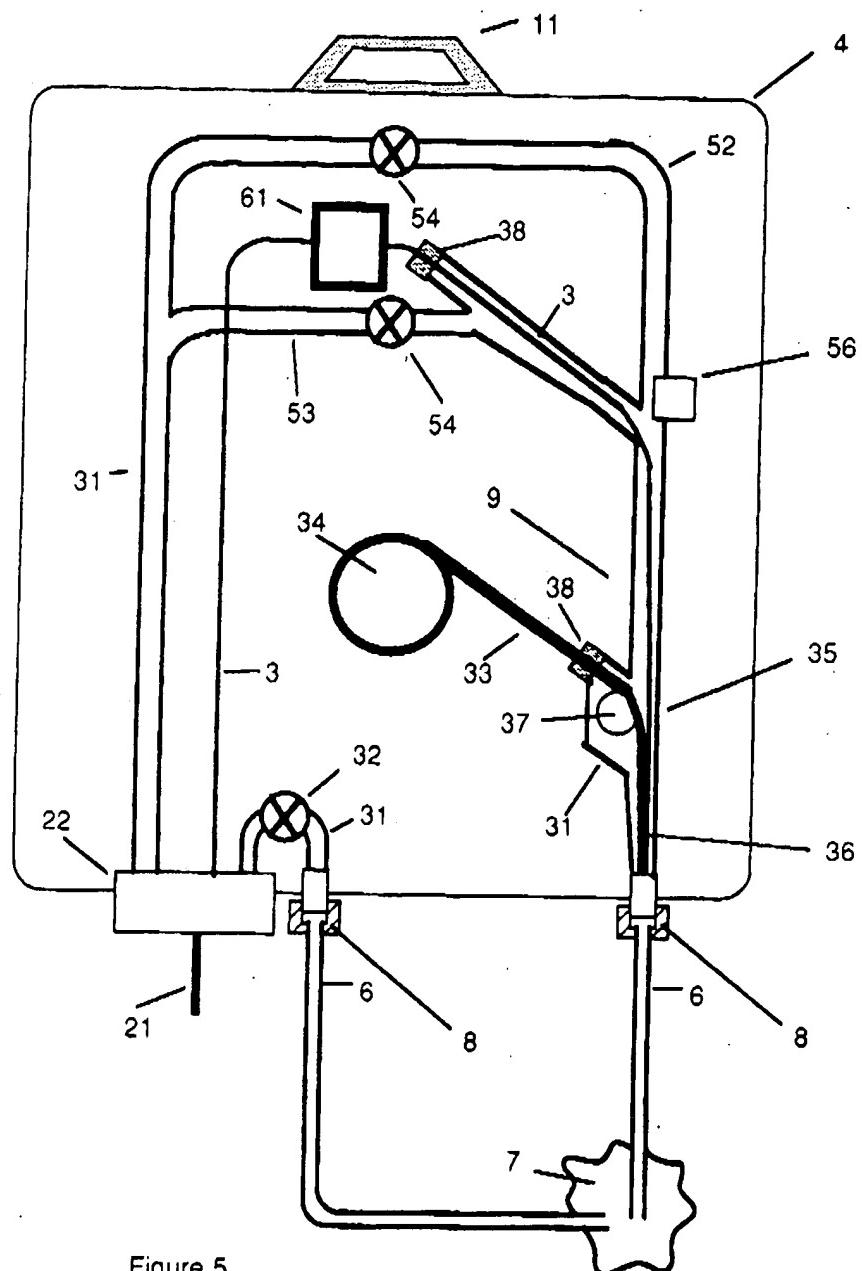


Figure 5

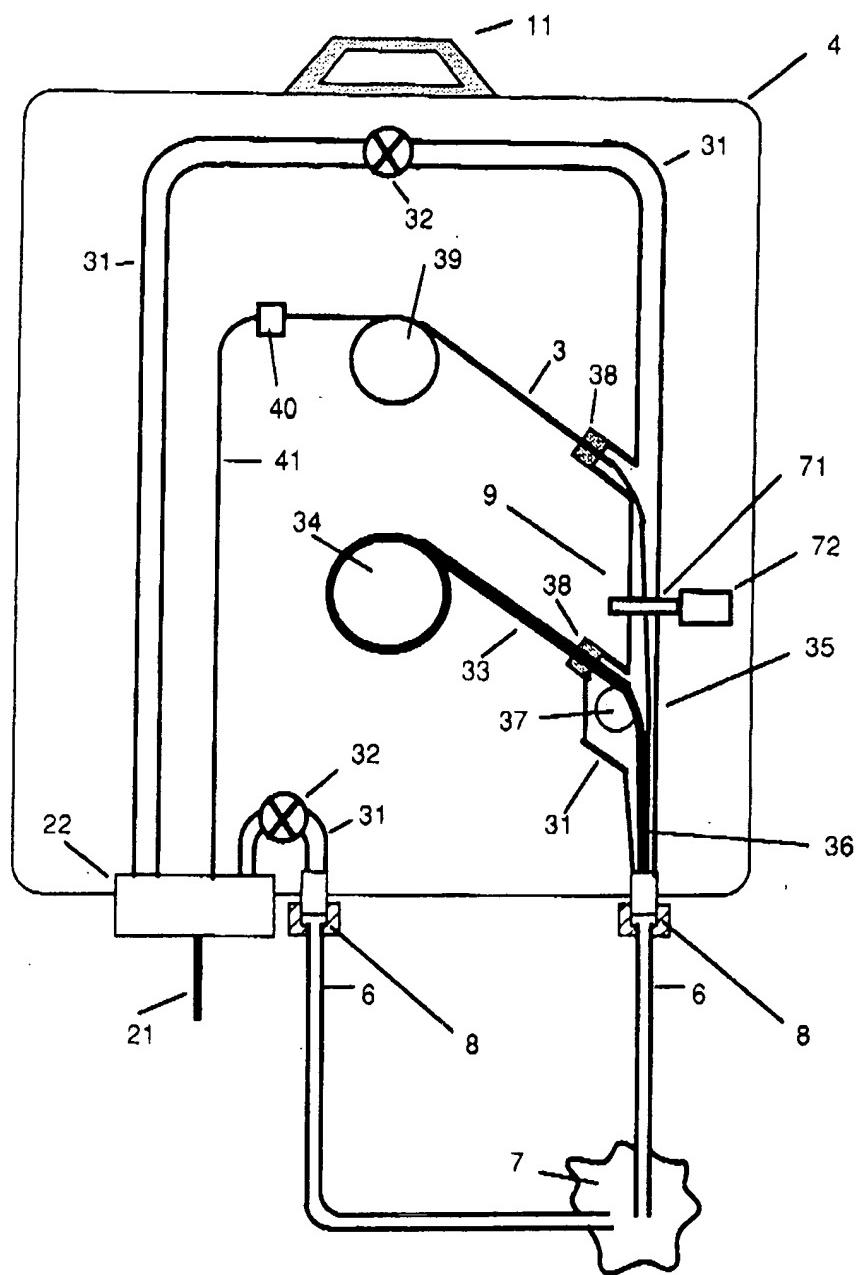


Figure 6

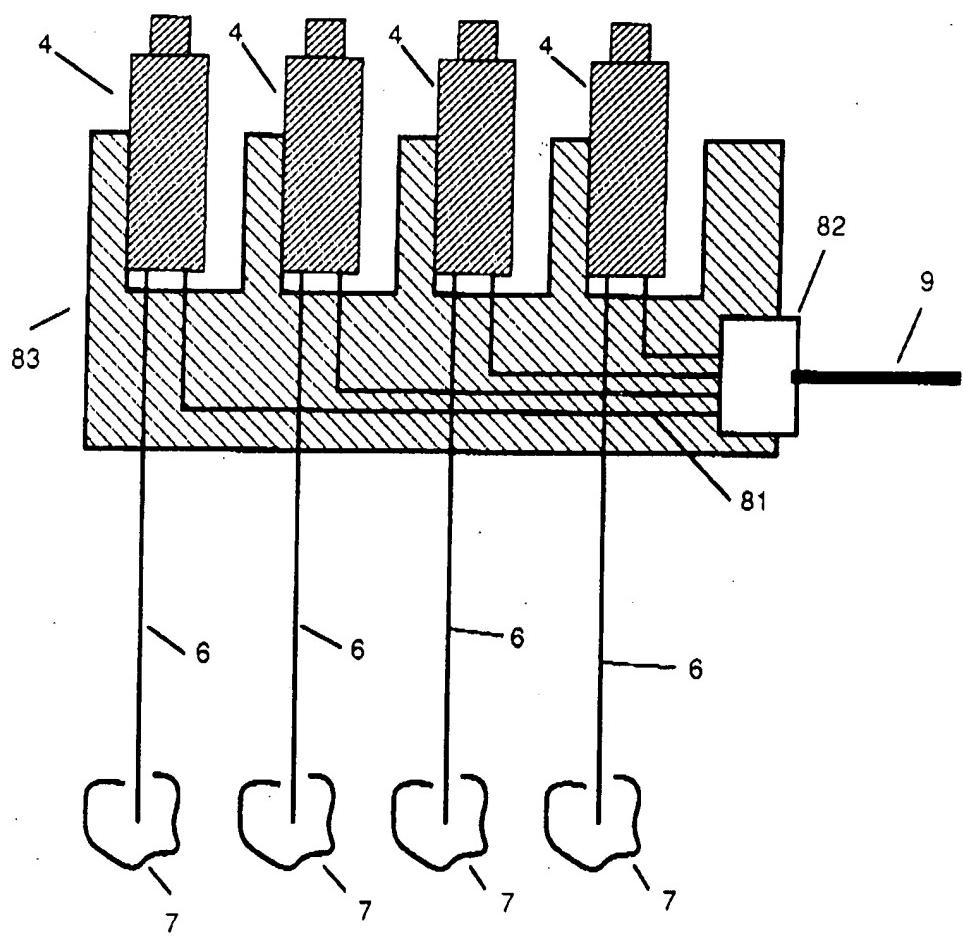


Figure 7

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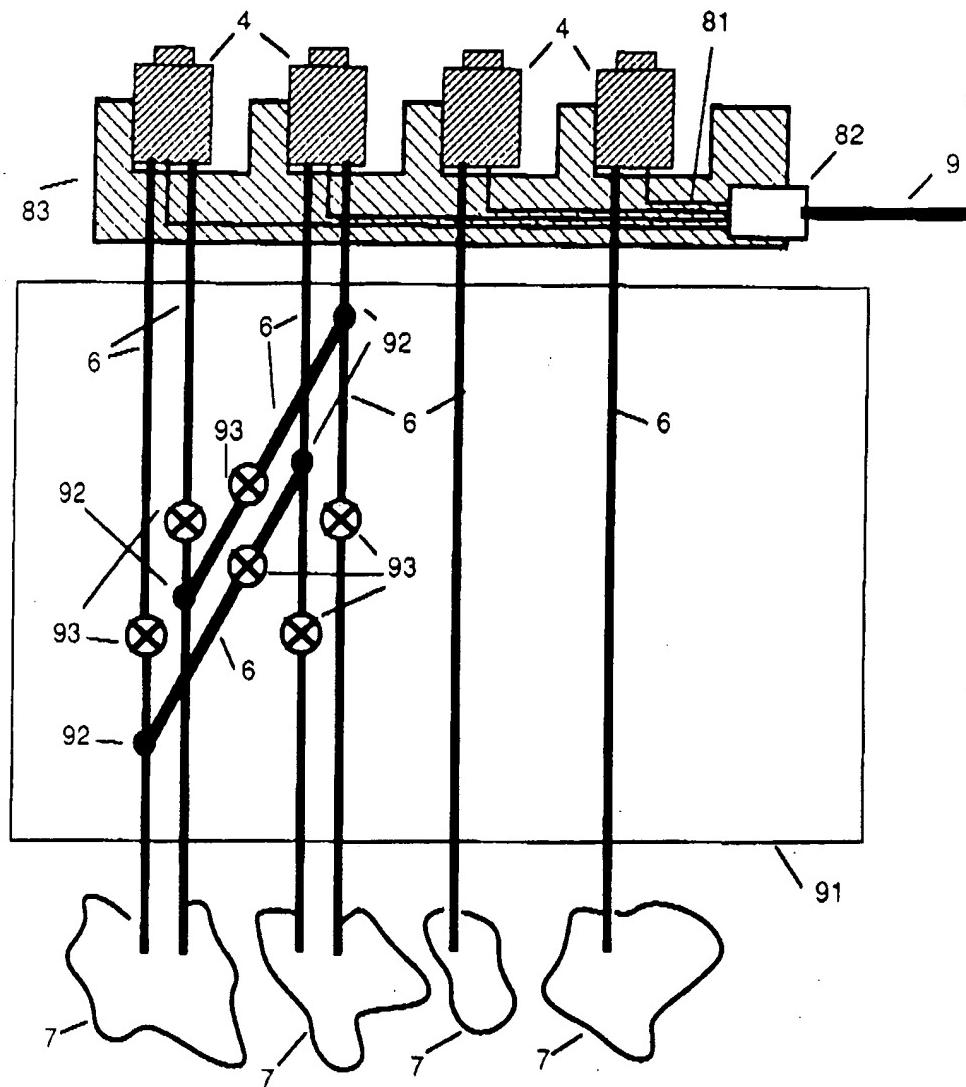


Figure 8

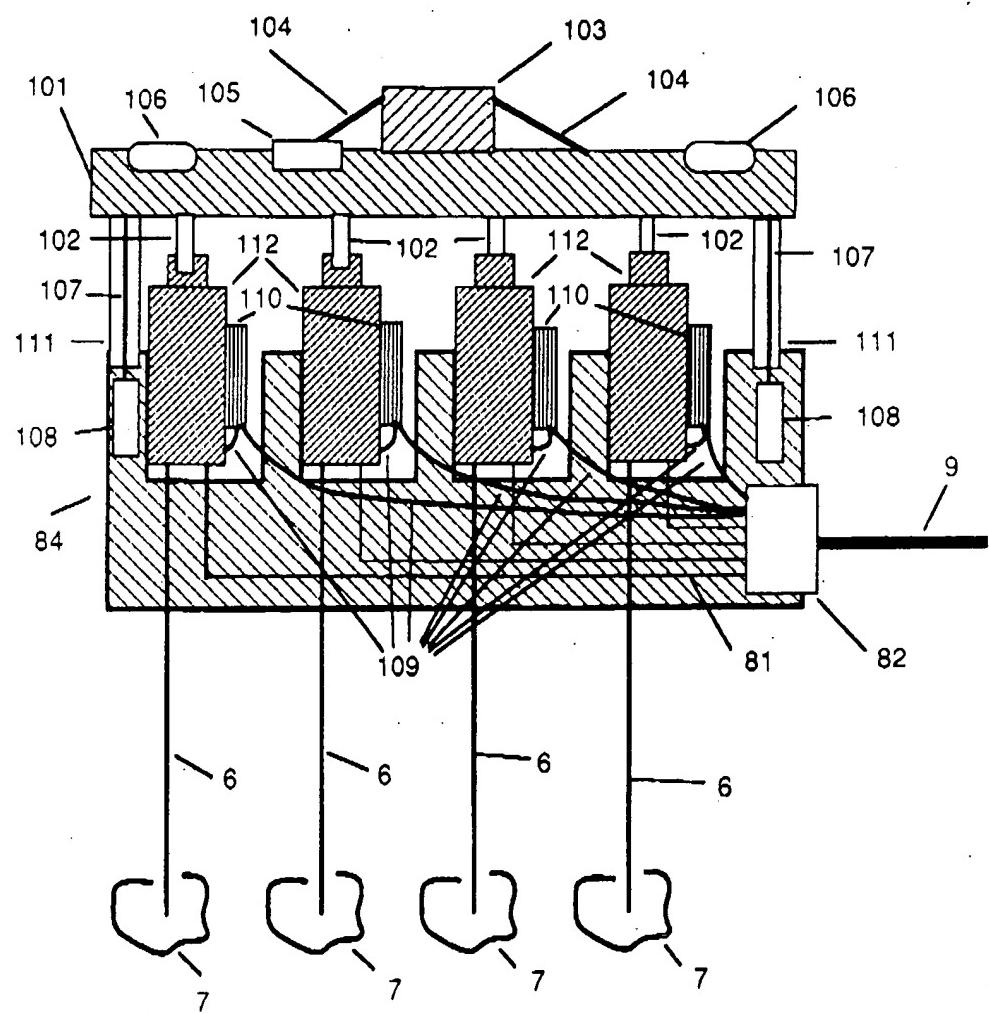


Figure 9

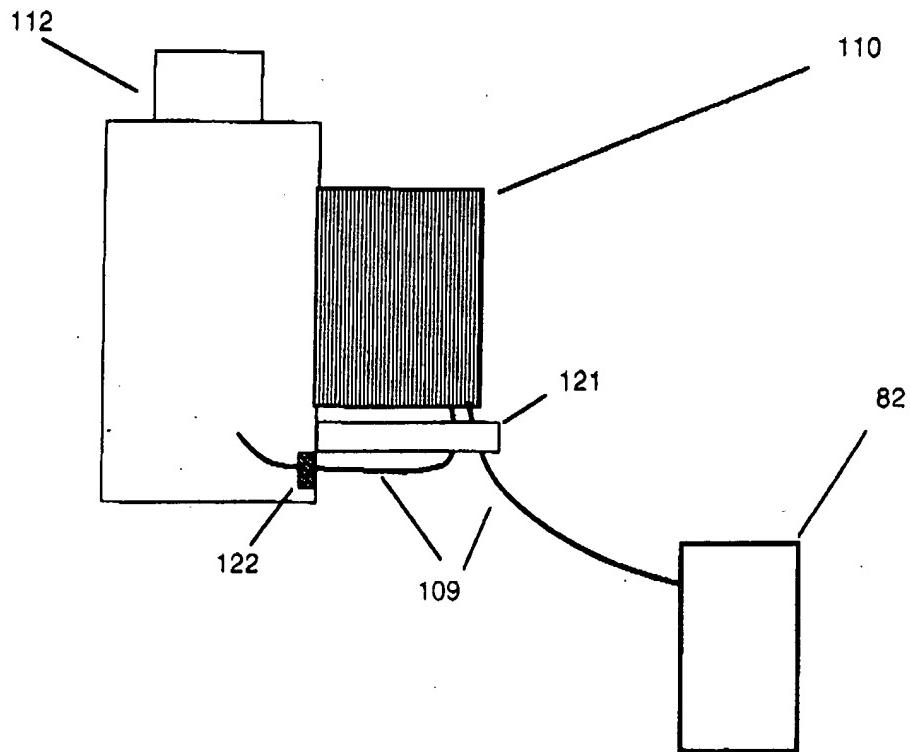


Figure 10

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